1	Original Article	
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2	Surgical invasiveness and lymphadenectomy in robotic and laparoscopic gastrectomy: A retrospective
3	study with propensity-score matching
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14	Sachiko Kaida: Conceptualization, methodology and writing-original draft; Satoshi Murata: Writing-review
15	and editing, supervision and project administration; Toru Miyake: Validation and formal analysis; Ken
16	Ishikawa: Software, data curation and resources; Tsuyoshi Yamaguchi: Investigation and resources;
17	Hiromitsu Maehira: Investigation and resources; Hiroya Iida: Data curation and resources; Katsushi
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- 8 declare.
- 9 Ethical approval: This study was approved by the Review Board of our institution and complied with the
- 10 guidelines stipulated in the Declaration of Helsinki.
- 11 **Informed consent:** Informed consent was obtained from all eligible patients who agreed to participate.

1 Abstract

2 Background

- 3 There is no consensus amongst comparative studies about the advantages of robotic over laparoscopic surgeries
- 4 for gastric cancer (GC). We compared invasiveness and lymph node dissection between robotic and
- 5 laparoscopic gastrectomies (RG and LG).

6 Methods

- 7 We retrospectively reviewed the medical records of 215 consecutive patients with GC who underwent RG or
- 8 LG with lymphadenectomy from January 2011–December 2020. Propensity score matching analysis was
- 9 performed to control selection bias.

10 Results

- 11 The RG group had less operative blood loss (*P*=0.0005) and higher C-reactive protein levels on postoperative
- day 1 (*P*=0.0006) than the LG group. When analyzing the specific sites of dissected lymph nodes, station groups
- of supra-pancreatic and lesser curvature areas accounted for this difference (P=0.0073 and 0.0362, respectively).

14 Conclusions

- 15 RG demonstrated lesser intraoperative bleeding, less of a postoperative inflammatory response, and a higher
- 16 proportion of lymph node removal than LG, suggesting that it is a better surgical and oncological procedure.
- 17 Keywords: robotic surgical procedures, laparoscopy, gastrectomy, gastric cancer, lymph node dissection

18

1 Introduction

2	Gastric cancer (GC) remains the fourth leading cause of cancer-related mortality worldwide, and over one
3	million new cases occurred in 2018. ¹ Recently, the use of robotic surgery as a minimally invasive treatment for
4	GC has become widespread, and the number of patients treated for this morbidity has increased. ² Several studies
5	have compared the short-term results of robotic gastrectomy (RG), laparoscopic gastrectomy (LG), and open
6	gastrectomy (OG), ^{3,4} and revealed less bleeding and lower complications rates in RG than in LG. ⁵⁻⁷ However, it
7	is still unclear whether RG has an advantage over LG regarding minimal invasiveness and lymph node (LN)
8	dissection techniques. Therefore, we compared the short-term outcomes and site-specific LN dissection in RG
9	and in LG using propensity-score matched cohorts.
10	
11	Methods
11 12	Methods Study design and patient selection
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1	Review Board of our institution, and the study complied with the guidelines stipulated in the Declaration of
2	Helsinki. Informed consent was obtained from all eligible patients who agreed to participate. This study is being
3	reported in line with the STROCSS 2019 Guideline.
4	The exclusion criteria were residual GC, neoadjuvant chemotherapy, conversion to open surgery before LN
5	dissection completion, LN D1 dissection, proximal gastrectomy, and incomplete clinical data. Cases with
6	residual GC were excluded. Overall, 215 patients (44 and 171 underwent RG and LG, respectively) were
7	eligible for analysis.
8	Disease assessment and variable definition
9	The age, sex, body mass index (BMI), and American Society of Anesthesiologists Physical Status (ASA-PS)
10	were recorded. In all cases, GC diagnosis and staging were performed using thoracoabdominal contrast-
11	enhanced computed tomography (CT), upper gastrointestinal endoscopy with biopsy, ultrasound endoscopy, and
12	positron emission tomography (PET)-CT for patients with advanced GC. After tumor staging was performed, all
13	LNs were eliminated by the operating surgeons (Figure 1) according to the Japanese classification of gastric
14	carcinoma: 3 rd English edition. ⁸ Surgical complications were classified according to the Clavien–Dindo system. ⁹
15	Postoperative pancreatic fistula was defined as an abdominal drainage fluid with amylase activity three times
16	higher than the upper normal limit of the serum value; grading was based on the updated consensus of the
17	International Study Group on Pancreatic Surgery. ¹⁰

18 Surgical procedures and lymph node classification

1	The standard procedure at our institution was a distal or total gastrectomy with D1+ or D2 regional LN
2	dissection, according to the Japanese Gastric Cancer Treatment Guidelines. ¹¹ In clinical stage I tumors, LG with
3	D1+ LN dissection was performed. LNs from the resected specimen were sent for pathological examination for
4	diagnosis of metastases. All LG and RG procedures were performed or guided by Endoscopic Surgical Skill
5	Qualification System (ESSQS)-qualified surgeons. ESSQS was launched in 2004 by the Japanese Society for
6	Endoscopic Surgery to develop a tool to reliably evaluate trainees' surgical techniques. ¹² Moreover, RG was
7	performed by surgeons certified to operate a da Vinci Surgical Sysyem (DVSS) console who were ESSQS
8	qualified and certified by the Japanese Society of Gastroenterological Surgery.
9	Laparoscopic gastrectomy
10	Six ports were used, and the left liver lobe was elevated as previously described. ¹³ First, the omentum of the
11	greater curvature was resected using an ultrasonically activated incision device (Harmonic Scalpel TM , Echicon
12	Endo-Surgery, Cincinnati, OH, USA). Then, the left gastroepiploic artery was dissected proximal to the first
13	branch, clipped, and ligated. The omentum was opened to reach the gastrocolic trunk, and the right
14	gastroepiploic vein and artery were clipped and ligated at their root. The duodenum was dissected using a
15	Signia TM tri-stapling system (Covidien Japan, Tokyo, Japan). The root of the right gastric artery was exposed
16	and ligated, and LNs at station 5 were dissected. While dissecting the supra-pancreatic LNs (stations 8a, 9, and
17	11p), the assistant carefully manipulated the pancreas caudally using gauze to prevent damage. Subsequently,
18	the left gastric artery and vein were isolated, ligated, and sectioned at their root, and LNs at station 9 were
19	dissected. Additionally, during the dissection of LNs at station 11p, the body and tail of the pancreas were rolled

1	and protected with a gauze while sealing the bottom of the LNs. For LN dissection near the lesser curvature, the
2	assistant grasped the lymphoid tissue from the ventral side applying tension, and the surgeon resected the LNs.
3	The oral side of the stomach or abdominal esophagus were also dissected in the proper position using a Signia TM
4	tri-stapling system, and the specimen was removed through a small incision wound above the umbilicus.
5	For reconstruction, Roux-en-Y (R-Y) anastomosis was performed for total gastrectomy. For distal gastrectomy,
6	R-Y anastomosis was selected in the following cases: tumor close to the duodenum; the remaining stomach was
7	< 1/3rd; or there was hiatal hernia. In all other cases, B-I reconstruction was selected. With the exception of the
8	jejunojejunostomy in R-Y anastomosis, all reconstructions were performed laparoscopically. Jejunojejunostomy
9	was performed approximately 30 cm distal to the ligament of Treitz through a small laparotomy (3-4 cm) from
10	which the creating was removed
10	which the specificity was removed.
11	Robotic gastrectomy
10 11 12	Robotic gastrectomy All RGs were performed using the da Vinci Si TM . The robot was inserted at 0° (aligned with the body's sagittal
11 12 13	Robotic gastrectomy All RGs were performed using the da Vinci Si TM . The robot was inserted at 0° (aligned with the body's sagittal axis) for distal gastrectomies and at 15° to the left for total gastrectomies. A Harmonic Scalpel TM or monopolar
11 12 13 14	Robotic gastrectomy All RGs were performed using the da Vinci Si TM . The robot was inserted at 0° (aligned with the body's sagittal axis) for distal gastrectomies and at 15° to the left for total gastrectomies. A Harmonic Scalpel TM or monopolar curved scissors, fenestrated bipolar forceps, and Cadiere forceps were used on the first, second, and third arms,
11 12 13 14 15	Robotic gastrectomy All RGs were performed using the da Vinci Si TM . The robot was inserted at 0° (aligned with the body's sagittal axis) for distal gastrectomies and at 15° to the left for total gastrectomies. A Harmonic Scalpel TM or monopolar curved scissors, fenestrated bipolar forceps, and Cadiere forceps were used on the first, second, and third arms, respectively. The assistant's 12-mm port was implanted to the right of the umbilicus, and pneumoperitoneum
11 12 13 14 15 16	Robotic gastrectomy All RGs were performed using the da Vinci Si TM . The robot was inserted at 0° (aligned with the body's sagittal axis) for distal gastrectomies and at 15° to the left for total gastrectomies. A Harmonic Scalpel TM or monopolar curved scissors, fenestrated bipolar forceps, and Cadiere forceps were used on the first, second, and third arms, respectively. The assistant's 12-mm port was implanted to the right of the umbilicus, and pneumoperitoneum was created at 10 mmHg using AirSeal TM (SurgiQuest, Orange CT, USA).
11 12 13 14 15 16 17	Robotic gastrectomy All RGs were performed using the da Vinci Si TM . The robot was inserted at 0° (aligned with the body's sagittal axis) for distal gastrectomies and at 15° to the left for total gastrectomies. A Harmonic Scalpel TM or monopolar curved scissors, fenestrated bipolar forceps, and Cadiere forceps were used on the first, second, and third arms, respectively. The assistant's 12-mm port was implanted to the right of the umbilicus, and pneumoperitoneum was created at 10 mmHg using AirSeal TM (SurgiQuest, Orange CT, USA). The basic procedures in RG and LG have the following differences. First, the suprapancreatic LNs dissection in
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1	operative field remained wide because the robot elevated each port. Second, in RG, when dissecting the left
2	gastric vein, scissors with articulated function attached to the first arm were used for sectioning, thus preventing
3	thermal damage to the pancreas and sparing the need for pancreatic protection. Additionally, since dissection of
4	station 11p was performed using monopolar curved scissors, rolling of the body and tail of the pancreas was not
5	necessary. However, to prevent lymphatic fistula at the base of station 11p, Harmonic Scalpel TM was used.
6	Third, the dissected tissue was grasped by the assistant in LG, but in RG, the third arm of the robot grasped,
7	fixed, and towed the tissue.
8	Propensity score matching
9	Propensity score matching (PSM) analysis was performed to reduce potential selection bias using the following
10	covariates: age, sex, BMI, operation method, LN dissection (D1+ or D2), and pathological stage. Then, the two
11	groups were matched using the nearest-neighbor matching algorithm (ratio=1:1 without replacement) with a
12	caliper width of 0.1 of the standard deviation of the propensity score logit. After PSM, 68 patients (34 patients
13	in each of the RG and LG groups) were eligible for analysis.
14	Statistical analysis
15	Statistical analyses were performed using the Fisher's exact test or the Mann-Whitney U-test, as appropriate.
16	Statistical calculations were performed using the Statistical Package for the Social Sciences for Mac (version
17	22.0, IBM Institute, Armonk, NY, USA) and GraphPad Prism version 8.0 (GraphPad Software, San Diego, CA,
18	USA). The Kaplan–Meier method was used to calculate overall survival (OS) and relapse-free survival (RFS),
19	and differences between the survival curves were assessed using the log-rank test. Multivariate analyses for

1	survival were performed using the Cox proportional hazard model. OS was calculated from date of surgery to
2	the date of all-cause death. RFS was calculated from date of surgery until recurrence and censored at death. For
3	all analyses, differences were considered statistically significant when P-value was < 0.05.
4	
5	Results
6	Baseline characteristics
7	Table 1 presents a comparison of baseline characteristics between the two groups before and after PSM. Prior to
8	PSM, the cancer stage was significantly higher in the RG group than in the LG group (P<0.0001); therefore, the
9	percentage of D2 dissection was also significantly higher in the RG group (P<0.0001). After PSM, both groups
10	were comparable in terms of age, sex, BMI, cancer stage, and ASA-PS.
11	Surgical characteristics and perioperative outcomes
12	Table 2 shows a comparison of surgical details and outcomes between the two groups before and after PSM.
13	Prior to PSM, there was no difference between groups in the type of operative procedure (distal or total
14	gastrectomy), operative time, postoperative complications, length of stay, or mortality. There was no difference
15	in the number of ESSQS-certified surgeons who performed the surgeries. Laboratory data revealed that blood
16	leukocyte count and drainage fluid amylase levels were comparable among the groups; C-reactive protein (CRP)
17	levels on postoperative day 1 were higher in the RG group than in the LG group ($P=0.0004$). Additionally, the
18	RG group had less blood loss (P<0.0001) and a higher number of LNs retrieved (P=0.0200) than the LG group.

1	A significantly larger number of LNs were retrieved in the RG group than in the LG group from the area of
2	stations 7, 8a, 9 and 11p, when examining dissections by site (Table 3 left).
3	After PSM, a significant reduction in intraoperative blood loss was observed in the RG group compared to the
4	LG group (P=0.0005). Additionally, the incidence of postoperative complications, length of stay, or mortality,
5	the RG group had significantly lower CRP levels on postoperative day 1 (P=0.0006) (Table 2).
6	Moreover, the number of LNs retrieved remained significantly higher in the RG group than in the LG group
7	(P=0.015). Specifically, LNs retrieved from the station groups of supra-pancreatic (7,8a,9 and 11p) and lesser
8	curvature (1, 3a, 3b and 5) areas accounted for this difference (<i>P</i> =0.0073 and 0.0362, respectively) (Table 3).
9	Survivals
10	The median follow-up periods were 1842 (range 271–2763) days for LG and 850 (range 142–1501) days for
11	RG, respectively. Figure 2 shows the Kaplan-Meier curves for patients undergoing RG and LG after PSM.
12	There were no significant differences between the LG and RG groups in both OS (log-rank <i>P</i> =0.46; Figure 2A)
13	and RFS (log-rank <i>P</i> =0.46; Figure 2B), although the survival of RG tended to be higher than that of LG.
14	
15	Discussion
16	In this study, we compared the short-term outcomes of RG and LG for GC and found that the RG was associated
17	with less bleeding, lower CRP levels at postoperative day 1, and a higher number of dissected LNs, suggesting
18	that a randomized controlled trial is worth conducting to confirm that RG is less invasive and has oncological
19	advantages.

1	The use of RG for GC has been increasing since Hashizume first performed it in Japan in 2003. ¹⁴ Two large-
2	scale multi-institutional prospective studies, one conducted in Japan ² and the other in Korea, ¹⁵ have compared
3	robotic and laparoscopic approaches for GC. Many smaller studies comparing short- and long-term outcomes
4	have also been reported. Among them, two randomized controlled trials have reported significantly less blood
5	loss with RG than with LG or OG in the short term. ¹⁶ In our study, RG resulted in less intraoperative bleeding
6	and a lower CRP value on the first day after surgery compared to LG. RG may be a minimally invasive surgery
7	that causes mild postoperative inflammation.
8	Many studies have shown that the number of dissected LNs determines the quality of cancer surgery. ¹⁷⁻²²
9	Lymphadenectomy is an important part of GC surgery because the number of dissected LNs may influence the
10	prognosis of patients. ²³ In this regard, our study showed that RG could be used to retrieve a significantly
11	increased number of LNs in specific areas compared with LG, suggesting that RG may be a superior surgical
12	technique for LNs dissection. However, survival-based assessments such as OS and RFS are needed to show the
13	oncological superiority of surgery. In this study, RG was superior to LG in terms of OS and RFS, but no
14	significant difference was established; however, this might be due to the small number of cases and the short
15	observation period. Therefore, a large prospective study that includes many cases is needed for the oncological
16	evaluation of RG for GC.
17	Postoperative pancreas-related complications results can help to examine the superiority of RG over LG in LN
18	dissection. The rates of pancreatic fistula after RG have been reported to be lower (approximately 0%-0.9%)
19	than those of LG $(0.5\%-5\%)$. ²⁴⁻²⁷ The reasons for a higher incidence of this complication after LG may include

1	the use of straight forceps and the fact that the pancreas needs to be mobilized with gauze. Additionally, Ojima
2	et al. ²⁸ reported that supra-pancreatic LN dissection without manipulating the pancreas is possible in RG. They
3	have found that the number of dissected LNs was higher and the postoperative day 1 drain amylase levels were
4	lower in RG than in LG. Additionally, they demonstrated that the robot had a stable traction force and the
5	articulated monopolar curved scissors could dissect LNs without compressing the pancreas. To evaluate the
6	surgical superiority of the number of resected LNs, we conducted a detailed study by comparing the number of
7	LNs at specific areas, which is a previously unreported method. As a result, RG could remove significantly
8	more LNs in the supra-pancreatic area (stations 7, 8a, 9 and 11p) than LG, but there was no increase in
9	postoperative drain amylase levels.
10	Considering the reports on the frequency of pancreas-related complications, the reasons for the surgical
11	advantage of RG regarding LN dissection may include the following: 1) all the ports in RG were lifted up
12	ventrally by the robot to keep the intra-abdominal cavity wide and to prevent interference between the pancreas
13	and forceps; 2) a strong and stable third arm could hold the pedicle of the left gastric artery, and the Harmonic
14	Scalpel TM was actively used for supra-pancreatic LN dissection, taking advantage of its sealing effect.
15	Although the number of LNs obtained was based on the surgical procedure using PSM analysis, the following
16	selection biases still existed when interpreting this result. First, regarding the supra-pancreatic LN dissection of
17	distal gastrectomy, the main difference between D1+ and D2 dissection is whether or not the No.11p LN was
18	retrieved. Due to the high visibility and maneuverability of the RG, the No. 11p LNs may have been
19	unintentionally removed beyond the range defined as D1+. Therefore, such excess excised LNs might have been

1	included in the number of supra-pancreatic areas. Second, there was a significant difference between RG and
2	LG in terms of the number of LN dissections on the lesser curvature areas, which may be difficult to explain by
3	the difference in surgical procedures. Many surgeons in our study performed the LN removals from the resected
4	specimens after gastrectomy. Therefore, surgeon bias may have affected the number of LNs extracted from the
5	resected specimens. After these biases are taken into account, it may be considered that performing RG for LN
6	dissection in the supra-pancreatic areas is not inferior to LG, but rather has an advantage equal to or higher than
7	that of LG. Therefore, a more detailed study-with limited cases involving D2 LN dissection and inclusion of
8	cases with PSM of surgeons who remove the LNs from the specimen—is warranted.
9	In this retrospective analytical study, we performed PSM which demonstrated the potential benefit of RG over
10	LG in terms of the number of LNs removed, suggesting that RG has a potential advantage in resection in GC
11	surgery. However, one of the problems with this is the difference in the timing of LG and RG. LG began seven
12	years before RG, and RG started after LG technique became stable. Thus, some of the initial LG data may be
13	more susceptible to the learning curve than those of RG. Another problem is the potential bias in the proficiency
14	of surgeons who performed LG or RG. For LG in this study, four ESSQS-qualified surgeons ensured the quality
15	of surgery as an operator or as a supervisor, while only two of the four ESSQS-qualified surgeons exclusively
16	performed RG. The surgeon bias could not be adjusted for using PSM. Therefore, a randomized controlled trial
17	should be conducted to verify the superiority of surgery performed only by skilled surgeons who have reached
18	the learning curve plateau.

1	This study has some limitations. First, this was a single-center study. The number of cases was subjectively
2	selected by surgeons, and since RG is newer than LG, the number of patients undergoing this procedure was
3	smaller. However, it was possible to confirm the difference by matching the background factors with PSM to
4	compensate for the small sample size. Second, this was a retrospective study. The surgical approach was
5	determined by the operator and patient. Although our results suggest that RG was associated with superior
6	outcomes, these should be validated in a randomized controlled trial. Additionally, future studies may obtain
7	results that are more reliable by increasing the sample size in both groups and comparing outcomes in multi-
8	center settings.
9	Conclusion
10	RG resulted in less intraoperative bleeding and lower CRP levels on the first day after surgery compared with
11	LG, indicating that the former is less invasive. Moreover, RG resulted in more effective LN dissection in the
12	supra-pancreatic region than LG, suggesting that it also has the potential to grow into an oncologically better
13	surgical procedure than LG.
14	
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- 1 Data Statement: The data that support the findings of this study are openly available in Mendeley Data at
- 2 "https://data.mendeley.com/drafts/f5kxv6hbx9".
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- 4

5 Figure legends

- 6 **Figure 1.** Lymph node stations, as defined by the Japanese classification of gastric carcinoma (3rd English
- redition) were classified into the following three areas: 1) greater curvature area, 2) lesser curvature area and 3)
- 8 supra-pancreatic area.
- 9 Figure 2. Kaplan-Meier estimates of (A) overall survival and (B) relapse-free survival probability after the
- 10 cohort was propensity-score-matched.

Table 1 Patients' characteristics

	Before PSM						After PSM					
	RG (n	= 44)	LG (n= 171)		P value	RG (n= 34)		LG (n= 34)		P value		
Age, years, median [range]	71	[24 - 86]	69	[30 - 90]	0.357	69	[24 - 86]	69	[30 - 82]	0.367		
Sex					0.381					1.0		
Male (%)	25	(56.8)	111	(64.9)		19	(55.9)	18	(52.9)			
Female (%)	19	(43.2)	60	(35.1)		15	(44.1)	16	(47.1)			
Body Mass Index (kg/m ²) [range]	22.4	[16.1 - 32.0]	22.6	[15.1-30.7]	0.46	23.1	[16.1 - 32.0]	23.2	[19.2-29.9]	0.189		
cStage†					< 0.0001					1.0		
ΙΑ	30	(68.2)	161	(94.1)		30	(88.2)	29	(85.3)			
IB	4	(9.1)	8	(4.7)		2	(5.9)	3	(8.8)			
II<	10	(22.7)	2	(1.2)		2	(5.9)	2	(5.9)			
Lymph node dissection					< 0.0001					>0.999		
D1+	30	(68.2)	161	(94.1)		30	(88.2)	29	(85.3)			
D2	14	(31.8)	10	(5.9)		4	(11.8)	5	(14.7)			
ASA-PS‡					0.71					0.94		
1	5	(11.4)	25	(14.6)		5	(14.7)	5	(14.7)			
2	36	(81.8)	130	(76.0)		25	(73.4)	24	(70.6)			
3	3	(6.8)	16	(9.4)		4	(11.8)	5	(14.7)			

Data are expressed as median (interquartile) or number of patients (percentage).

†: According to the 15th Japanese Classification of Gastric Carcinoma. ‡ASA-PS: American Society of Anesthetists Physical Status

Table 2 Intraoperative outcomes and surgical procedures

	Before	PSM				After	PSM			
	RG (n=	= 44)	LG (n=	= 171)	P value	RG (n=	= 34)	LG (n=	= 34)	P value
Operative procedure					0.53					0.79
Distal gastrectomy, n (%)	34	(77.2)	139	(81.3)		25	(73.5)	24	(70.6)	
Total gastrectomy, n (%)	10	(22.8)	34	(18.7)		9	(26.5)	10	(29.4)	
Operation time, min, median [range]	408	[234 - 639]	384	[209 - 931]	0.94	363	[234 - 639]	396	[226 - 638]	0.72
Blood loss, ml, median [range]	17	[0 - 251]	100	[0 - 4394]	< 0.0001	11	[0 - 251]	100	[0 - 960]	0.0005
Retrieved lymph nodes, number, median [range]	39	[7 - 95]	31	[9 - 68]	0.02	42	[19 - 81]	31	[13 - 61]	0.015
Any complication Clavien-Dindo Grade >2, n (%)	1	(2.2)	8	(4.6)	0.69	1	(2.9)	3	(8.8)	0.61
Hospital stay, days, median [range]	11	[7 - 30]	11	[7 - 108]	0.56	11	[7 - 30]	12	[7 - 65]	0.33
Amylase level in drainage fluid on POD1, IU/L, median [range]	503	[83 - 4080]	391	[35 - 26876]	0.27	471	[83 - 4080]	502	[88 - 26729]	0.83
Amylase level in drainage fluid on POD2, IU/L, median [range]	246	[37 - 2085]	211	[19 - 8130]	0.79	254	[37 - 2085]	250	[60 - 4301]	0.79
Amylase level in drainage fluid on POD3, IU/L, median [range]	158	[30 - 2154]	131	[31 - 3434]	0.59	158	[30 - 2154]	195	[30 - 809]	0.84
WBC on POD 1, /µL, median [range]	9200	[4100 - 14400]	9100	[4000 - 20500]	0.56	9250	[4100 - 14400]	8600	[4300 - 16400]	0.61
CRP on POD 1, mg/dL, median [range]	5.6	[0.2 - 9.8]	6.7	[2.3 - 18.3]	0.0004	5.1	[0.6 - 9.6]	7	[3.4 - 18.3]	0.0006
pStage†					< 0.001					0.94
IA	28	(63.6)	150	(87.7)		25	(73.5)	24	(70.6)	
IB	5	(11.4)	12	(7.0)		5	(14.7)	5	(14.7)	
II<	11	(25.0)	9	(5.3)		4	(11.8)	5	(14.7)	
Mortality, n (%)	0		0		n.s.	0		0		n.s.
ESSQS-qualified Surgeons, No	2		4		n.s.	2		4		n.s.

Data are expressed as median (interquartile) or number of patients (percentage).

CRP = C reactive protein, n.s. = not significant, WBC = white blood cell, POD = postoperative day, RG = robotic gastrectomy, LG = laparoscopic gastrectomy, ESSQS = Endoscopic Surgical Skill Qualification System.

†: According to the 15th Japanese Classification of Gastric Carcinoma.

Table 3 Comparison of the number of lymph node dissections by site

	Before PSM			After PSM			
	RG (n= 44)	LG (n= 171)	P value	RG (n= 34)	LG (n= 34)	P value	
#1,3a,3b,5	11 [2 - 34]	10 [1 - 31]	0.2617	12 [5 - 36]	9 [0 - 26]	0.0362	
#4d,6	10 [1 - 33]	9 [0 - 33]	0.2883	11 [3 - 31]	10 [0 - 24]	0.0989	
#7,8a,9,11p	12 [0 - 35]	10 [0 - 29]	0.0213	14 [5 - 35]	9 [0 - 23]	0.0073	
total	39 [7 - 95]	31 [9 - 68]	0.02	42 [19 - 81]	31 [13 - 61]	0.015	

Data are expressed as median [interquartile].

#LNs numbers are according to the 15th Japanese Classification of Gastric Carcinoma.

Figure 1



